

Math 314. Week 8 worksheet (§4.4, §4.5, §4.6).

A set of vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_t\}$  in a vector space (or subspace)  $V$  is a **basis** for  $V$  if it spans  $V$  and it is linearly independent.

If  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  is a basis for  $V$ , then every element of  $V$  can be written as a linear combination of these vectors

$$\mathbf{v} = c_1 \mathbf{b}_1 + \dots + c_n \mathbf{b}_n$$

in exactly one way. We say that the stack of numbers

$$[\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

is the vector of  $\mathcal{B}$ -coordinates of  $\mathbf{v}$ .

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A. COORDINATES FOR  $P_3$

- (1) The set  $\mathcal{B} = \{t^3, t^2, t, 1\}$  is a basis for  $P_3$ , the vector space of polynomials of degree at most 3. Find the  $\mathcal{B}$ -coordinates of the polynomial  $p(t) = 2^3 - t^2 + 3$ .

- (2) If  $[q(t)]_{\mathcal{B}} = \begin{bmatrix} 7 \\ -1 \\ 0 \\ \pi \end{bmatrix}$ , what is  $q(t)$ ?

- (3) Show that the set of polynomials  $\mathcal{C} = \{t^3 - 1, t^2 - 1, t - 1, 1\}$  is also a basis for  $P_3$ .

- (4) Find  $q(t)$  where  $[q(t)]_{\mathcal{C}} = \begin{bmatrix} 7 \\ -1 \\ 0 \\ \pi \end{bmatrix}$ .

- (5) Find  $[2^3 - t^2 + 3]_{\mathcal{C}}$ .

B. COORDINATES FOR A SUBSPACE OF  $\mathbb{R}^3$ . Consider the plane  $H$  given by the equation  $3x + 7y - 5z = 0$  in  $\mathbb{R}^3$ .


- (1)  $H$  is the null space of a matrix—which matrix?
- (2) Explain in five words or less why  $H$  is a subspace of  $\mathbb{R}^3$ .
- (3) Find a basis  $\mathcal{B}$  for  $H$ .
- (4) Using the basis you found, determine the point on  $H$  with  $\mathcal{B}$ -coordinates  $[1, 1]^T$ .
- (5) Using the basis you found, determine the  $\mathcal{B}$ -coordinates of  $[-1, -1, -2]^T$ .
- (6) Using the basis you found, can you find the  $\mathcal{B}$ -coordinates of  $[0, -1, -2]^T$ ?

C. DIFFERENT<sup>1</sup> COORDINATES ON  $\mathbb{R}^3$ . Let

$$\mathbf{b}_1 = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \mathbf{b}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \mathbf{b}_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, A = [\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3], \text{ and } \mathcal{C} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}.$$

- (1) Is  $\mathcal{C}$  invertible? If so, find the inverse of  $\mathcal{C}$ .
- (2) Is  $A$  invertible? If so, find the inverse of  $A$ .
- (3) Is  $A$  a basis for  $\mathbb{R}^3$ ?

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<sup>1</sup>  Trick questions ahead!

- (4) Is  $\mathcal{C}$  a basis for  $\mathbb{R}^3$ ?
- (5) Rewrite the expression  $c_1\mathbf{b}_1 + c_2\mathbf{b}_2 + c_3\mathbf{b}_3$  as a product involving the matrix  $A$  and a vector.
- (6) Explain why  $A[\mathbf{v}]_{\mathcal{C}} = \mathbf{v}$  for all vectors  $\mathbf{v} \in \mathbb{R}^3$ .
- (7) If  $[\mathbf{v}]_{\mathcal{C}} = [3, -1, -1]^T$ , then use the previous part to find  $\mathbf{v}$ .
- (8) Use part (2) to find the  $\mathcal{C}$ -coordinates of the vector  $[4, 0, 9]^T$ .

D. CHANGE-OF-COORDINATE MATRIX. If  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  is a basis for  $\mathbb{R}^n$ , then  $P_{\mathcal{B}} = [\mathbf{b}_1 \cdots \mathbf{b}_n]$  is called the  $\mathcal{B}$  change-of-coordinates matrix. Explain why  $P_{\mathcal{B}} \cdot [\mathbf{x}]_{\mathcal{B}} = \mathbf{x}$  and  $P_{\mathcal{B}}^{-1} \cdot \mathbf{x} = [\mathbf{x}]_{\mathcal{B}}$  for all  $\mathbf{x} \in \mathbb{R}^n$ .

DEFINITION: The **dimension** of a vector space  $V$  is the number<sup>2</sup> of vectors in any basis for  $V$ .

FACTS ABOUT DIMENSION: For an  $n$ -dimensional vector space  $V$ ,

- (1) The number of vectors in any basis for  $V$  is exactly  $n$ .
- (2) Any set of vectors that spans  $V$  has at least  $n$  elements.
- (3) Any linearly independent set of vectors has at most  $n$  elements.
- (4) If a set of  $n$  vectors is either linearly independent OR spans  $V$ , then it does both.

The dimension of the column space of a matrix is called its **rank**. This number is equal to the number of pivots. Furthermore,

$$\text{rank}(A) + \dim \text{Null}(A) = \# \text{ columns of } A.$$

E. DIMENSIONS OF COLUMN SPACES AND NULL SPACES. Find the dimension of  $\text{Col}(A)$  and  $\text{Null}(A)$ ,

where  $A = \begin{bmatrix} 1 & -7 & 8 & 1 & 5 \\ 0 & 1 & 3 & 0 & 8 \\ 0 & 0 & 0 & 7 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ .

F. USING THE RANK-NULLITY THEOREM. Let  $A$  be a  $4 \times 7$  matrix.

- (1) If the rank of  $A$  is 3, what is the dimension of  $\text{Null}(A)$ ?
- (2) If the dimension of  $\text{Null}(A)$  is 5, what is the rank of  $A$ ?
- (3) Can  $\dim \text{Null}(A) = 2$ ? Why or why not?
- (4) Suppose that  $A\mathbf{x} = \mathbf{b}$  always has a solution. What is  $\dim \text{Null}(A)$ ?
- (5) If the rank of  $A$  is three, then any set of four of the columns of  $A$  is [WHAT]?
- (6) If the rank of  $A$  is three, then can a set of three of vectors span the null space of  $A$ ?
- (7) Suppose that the solution set to  $A\mathbf{x} = [3, -1, 2, 6]^T$  is, in parametric vector form,

$$[1, 0, 1, 2, 8, 9, \pi]^T + r[e, \sqrt{2}, 0, 1, 2, 3, 4]^T + s[5, 5, 5, 0, 1, 9, 9]^T + t[8, 6, 7, 5, 3, 0, 9]^T, r, s, t \in \mathbb{R}.$$

What can you say about the rank of  $A$ ?

- (8) Suppose that the solution set to  $A\mathbf{x} = [3, -1, 2, 6]^T$  is  $\emptyset$ . What can you say about the rank of  $A$ ?

G. AN INFINITE DIMENSIONAL VECTOR SPACE. Explain why no finite set of polynomials spans the vector space  $P$  of polynomials (of any degree). Conclude that  $P$  is infinite-dimensional. Now find a basis for  $P$ .

<sup>2</sup>...if there is a finite set of vectors that is a basis for  $V$ . Otherwise, we say  $V$  is **infinite-dimensional**. Also, the dimension of the vector space  $\{\mathbf{0}\}$  is 0.

H\*. EVERYTHING ABOUT DIMENSION, ALMOST. Let  $V$  be a vector space. Suppose that the set  $\{\mathbf{v}_1, \dots, \mathbf{v}_m\}$  spans  $V$ , and  $\{\mathbf{w}_1, \dots, \mathbf{w}_n\}$  is another set of vectors in  $V$ .

- (1) Explain why there are a bunch of numbers  $a_{ij}$ , where  $i = 1, \dots, m, j = 1, \dots, n$ , such that

$$\begin{aligned}\mathbf{w}_1 &= a_{11}\mathbf{v}_1 + \cdots + a_{m1}\mathbf{v}_m \\ &\vdots \quad \quad \quad \vdots \\ \mathbf{w}_n &= a_{1n}\mathbf{v}_1 + \cdots + a_{mn}\mathbf{v}_m\end{aligned}$$

In short,  $\mathbf{w}_j = \sum_{i=1}^m a_{ij}\mathbf{v}_i$  for every  $j$ .

- (2) Put all these numbers  $a_{ij}$  into a matrix<sup>3</sup>  $A = [a_{ij}]$ . If  $n > m$ , explain why there is a nonzero vector  $\mathbf{b} = [b_1, \dots, b_n]^T$  in the null space of  $A$ . In short,  $\sum_{j=1}^n a_{ij}b_j = 0$  for every  $i$ .
- (3) Continuing the story from the previous part, show that  $\sum_{j=1}^n b_j\mathbf{w}_j = \mathbf{0}$ .
- (4) Conclude that  $S$  is *any* spanning set in  $V$ , and  $T$  is *any* linearly independent set on  $V$ , then  $S$  has at least as many elements as  $T$ .
- (5) Use the last observation to justify facts (1)–(3) about dimension.
- (6) Use part (4) to explain why  $\dim(H) \leq \dim(V)$  for a subspace  $H \subseteq V$ .

I\*. SOMETHING ABOUT RANK. Let  $A$  be an  $m \times n$  matrix, and  $B$  be an  $n \times k$  matrix.

- (1) Explain why  $\text{Col}(AB) \subseteq \text{Col}(A)$ .
- (2) Explain why  $\text{rank}(AB) \leq \text{rank}(A)$ .
- (3) Explain why  $\text{Null}(B) \subseteq \text{Null}(A)$ .
- (4) Explain why  $\text{rank}(AB) \leq \text{rank}(B)$ .
- (5) Is  $\text{rank}(AB) = \min\{\text{rank}(A), \text{rank}(B)\}$ ?

J\*. SOMETHING ELSE ABOUT BASES.

- (1) A set of vectors  $S$  in a vector space  $V$  is a *maximal linearly independent set* if  $S$  is linearly independent, and  $S \cup \{\mathbf{v}\}$  is linearly dependent for all  $\mathbf{v} \notin V$ . Explain why a maximal linearly independent set in  $V$  is a basis for  $V$ .
- (2) A set of vectors  $S$  in a vector space  $V$  is a *minimal spanning set* if  $S$  spans  $V$ , and  $S \setminus \{\mathbf{s}\}$  does not span  $V$  for all  $\mathbf{s} \in S$ . Explain why a minimal spanning set in  $V$  is a basis for  $V$ .

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<sup>3</sup>Beware of the numbering: if you take the numbers in the same relative places as in the equations above, then  $A$  is the transpose of that.