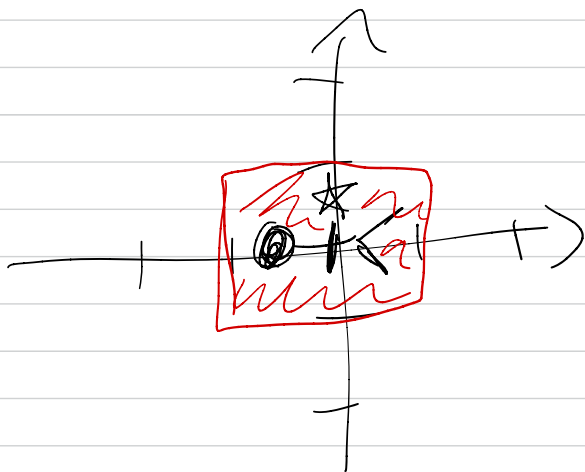


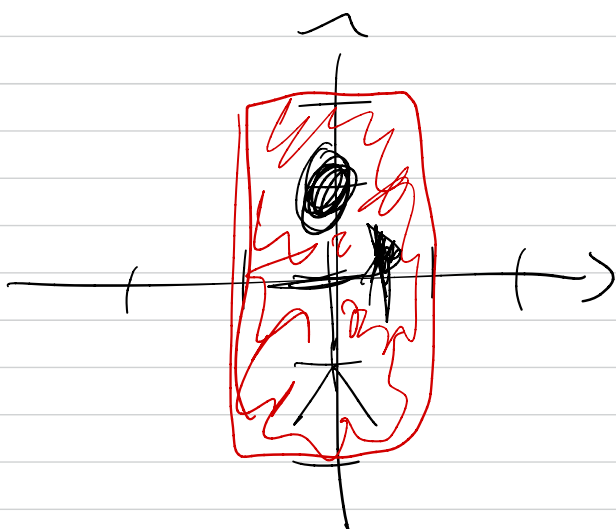
Worksheet #4 solutions

A 1)



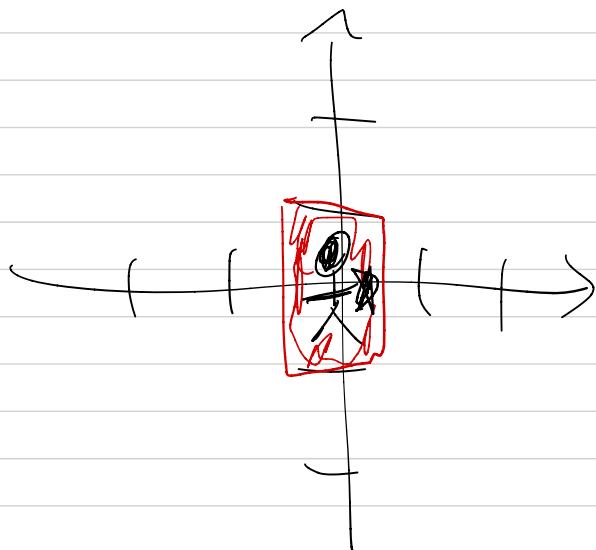
$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

2)



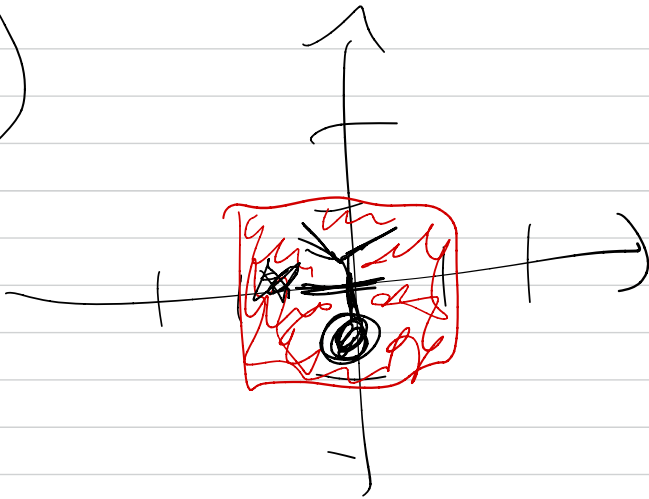
$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

3)



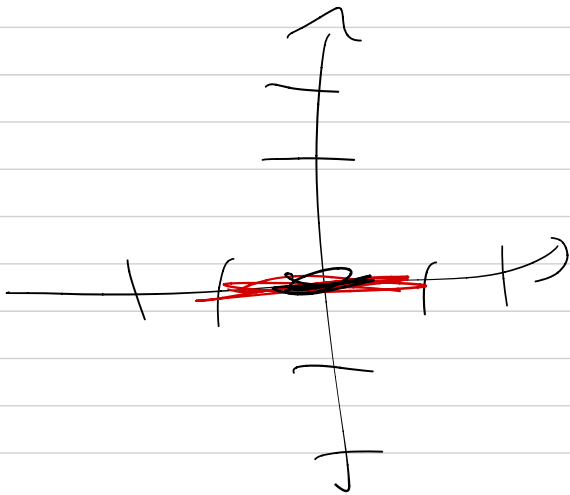
$$\begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix}$$

4)



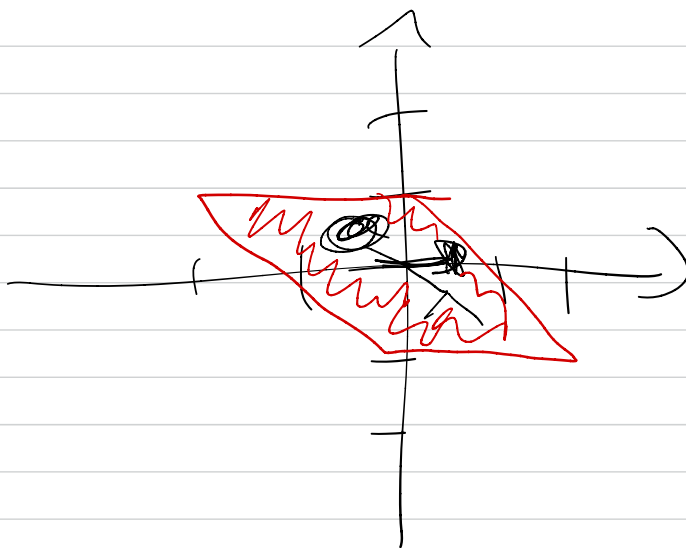
$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

5)



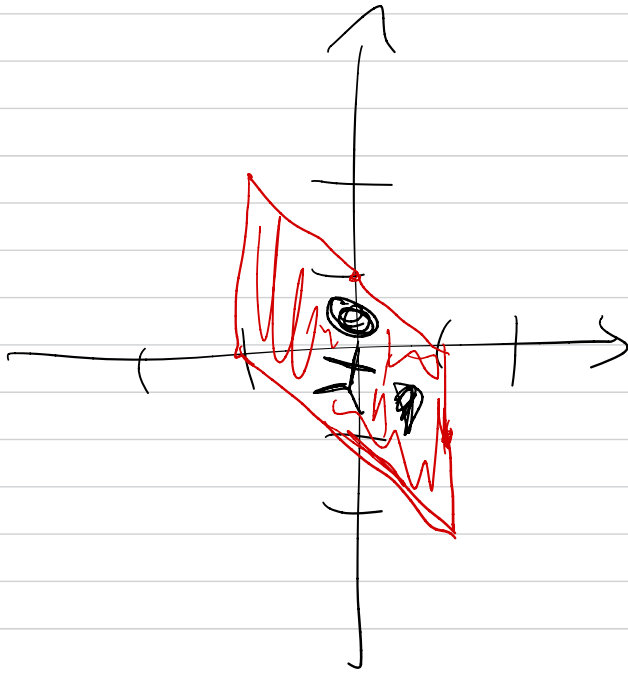
$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

B.1)



$$\begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

2)



$$\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

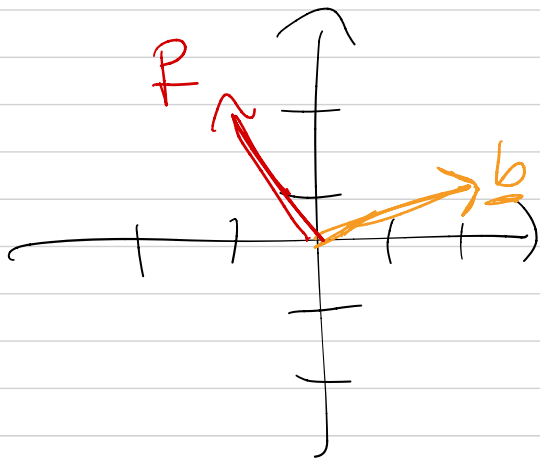
3)



$$\begin{bmatrix} 2 & 1 \\ -1 & 3 \end{bmatrix}$$

C. 1) $\mathbb{R}^2; \mathbb{R}^2$

2)



3) yes; onto

4) no; one-to-one

D. 1) $\mathbb{R}^2; \mathbb{R}^2$

2) $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$; no

3) $\begin{bmatrix} 0 \\ 0 \end{bmatrix} \neq \begin{bmatrix} 1 \\ 0 \end{bmatrix}$; no
(there are many answers)

E-1) $\mathbb{R}^5; \mathbb{R}^4$

2) $A \in \mathbb{R}^{4 \times 5}$ row equivalent to

$$\begin{bmatrix} 1 & -1 & 3 & -4 & 5 \\ 0 & 2 & 1 & 0 & 3 \\ 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix} \Rightarrow \text{onto but not one-to-one}$$

3) $A\underline{x} = \underline{b}$ is always consistent,
never unique solution.

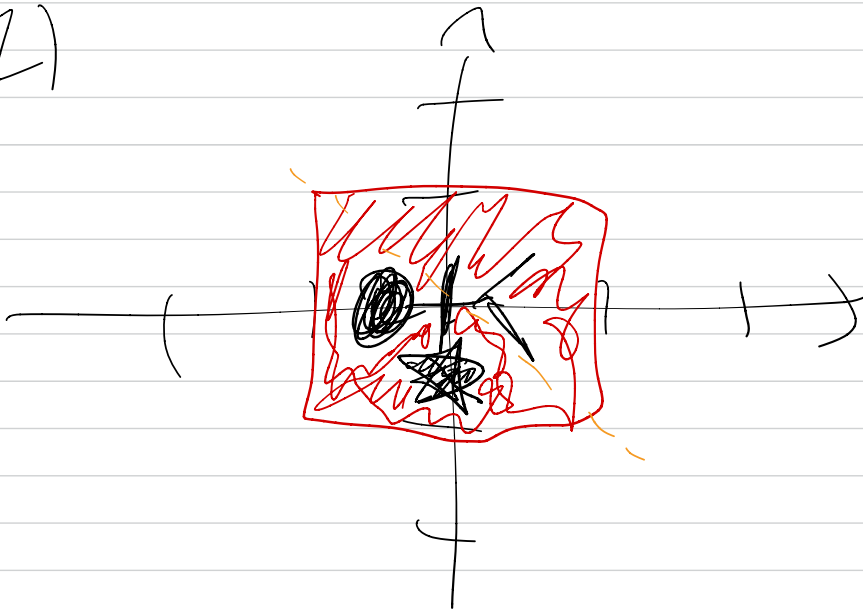
Every solution set is a line.

F. 1) no

2) yes: 2×2

3) yes: 5×5

6.1)



Reflection
over $y = -x$

2)

$$\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

3)

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

4)

$$\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

H. 1) From the theorem on the first page about standard matrices.

$$\begin{aligned} 2) (T \circ U)(\underline{e}_1) &= T(U(\underline{e}_1)) \\ &= T(\underline{b}_1) = A\underline{b}_1 \end{aligned}$$

3) Similarly,

$$(T \circ U)(\underline{e}_i) = A\underline{b}_i \text{ for each } i,$$

So standard matrix of $T \circ U$

$$\text{is } \begin{bmatrix} (T \circ U)(\underline{e}_1) & \dots & (T \circ U)(\underline{e}_n) \end{bmatrix}$$

$$= \begin{bmatrix} A\underline{b}_1 & \dots & A\underline{b}_n \end{bmatrix}.$$

$$I_1) A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}, B = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$

$$2) AB = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

rotation around line $x=y=z$!