

Math 314. Week 10 worksheet (§5.3, §5.4, §5.5).

If  $A$  is an  $n \times n$  matrix, then

$$A = PDP^{-1} \iff \begin{matrix} P = [\mathbf{b}_1 & \cdots & \mathbf{b}_n] \text{ where } \mathbf{b}_1, \dots, \mathbf{b}_n \text{ are } n \text{ linearly independent eigenvectors for } A \\ \text{with } D \text{ diagonal} & D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \text{ where } \lambda_i \text{ is the eigenvalue of } \mathbf{b}_i. \end{matrix}$$

DEFINITION: An  $n \times n$  matrix  $A$  is **diagonalizable** if we can write  $A = PDP^{-1}$  for some invertible matrix  $P$  and some diagonal matrix  $D$ .

THEOREM: An  $n \times n$  matrix  $A$  is diagonalizable if and only if the dimensions of its eigenspaces add up to  $n$ . When this happens, if you take a basis for each eigenspace, and combine these bases together, you get a set of  $n$  linearly independent eigenvectors for  $A$ .

THEOREM: If an  $n \times n$  matrix has  $n$  distinct eigenvalues, then it is diagonalizable. However, not every diagonalizable  $n \times n$  matrix has  $n$  distinct eigenvalues.

A. DIAGONALIZING A MATRIX. Let  $A = \begin{bmatrix} 0 & 1 \\ 2 & 1 \end{bmatrix}$ . Our goal in this problem diagonalize  $A$ .

- (1) Find the eigenvalues of  $A$ : compute the characteristic polynomial, and find its roots.
- (2) For each eigenvalue, find a basis for the eigenspace.<sup>1</sup>
- (3) Put together all of the bases for the different eigenspaces into one set; you should have 2 here. Stack them together to form  $P$ .
- (4) Put the corresponding eigenvalues on the diagonal in the some order to get  $D$ .

B. DIAGONALIZING ANOTHER MATRIX? Let  $B = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$ . Explain why the eigenvalues of  $B$  are 2 and 3. Find the dimensions of the  $\lambda = 2$  and  $\lambda = 3$  eigenspaces. Is  $B$  diagonalizable?

C. DIAGONALIZATION AND POWERS.

- (1) If  $D = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$ , find a formula for every<sup>2</sup> power  $D^n$  of  $D$ .
- (2) If  $D = \begin{bmatrix} 1/2 & 0 \\ 0 & 1/3 \end{bmatrix}$ , what happens to  $D^n$  as  $n \rightarrow \infty$ ?
- (3) If  $D = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ , what happens to  $D^n$  as  $n \rightarrow \infty$ ?
- (4) If  $A = PDP^{-1}$ , explain why  $A^n = PD^nP^{-1}$  for every<sup>3</sup>  $n$ .
- (5) If  $A$  is a  $2 \times 2$  matrix, and all of its eigenvalues are larger than 1, what happens to  $A^n$  as  $n \rightarrow \infty$ ?
- (6) If  $A$  is a  $2 \times 2$  matrix, and all of its eigenvalues are between 0 and 1, what happens to  $A^n$  as  $n \rightarrow \infty$ ?

<sup>1</sup>Remember that the  $\lambda$ -eigenspace is the null space of  $A - \lambda I$ .

<sup>2</sup>Hint: Start with  $n = 2$ , then  $n = 3, \dots$

<sup>3</sup>Hint: Start with  $n = 2$ , then  $n = 3, \dots$

DEFINITION: If  $T : V \rightarrow V$  is a linear transformation, and  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  is a basis for  $V$ , then the  **$\mathcal{B}$ -matrix of  $T$**  is the matrix such that  $[T]_{\mathcal{B}} \cdot [\mathbf{v}]_{\mathcal{B}} = [T(\mathbf{v})]_{\mathcal{B}}$  for all  $\mathbf{v} \in V$ . It is given by the formula

$$[T]_{\mathcal{B}} = \begin{bmatrix} [T(\mathbf{b}_1)]_{\mathcal{B}} & \cdots & [T(\mathbf{b}_n)]_{\mathcal{B}} \end{bmatrix}.$$

D. THE  $\mathcal{B}$ -MATRIX OF A LINEAR TRANSFORMATION ON POLYNOMIALS. Let  $P_3$  be the vector space of all polynomials of degree at most 3. Consider the function  $D : P \rightarrow P$  given by  $D(f(t)) = \frac{df}{dt}$ . We checked last time that this is a linear transformation. Take the basis  $\mathcal{B} = \{t^3, t^2, t, 1\}$  for  $P_3$ . Find the  $\mathcal{B}$ -matrix for  $D$ . Is it diagonalizable?

E. THE  $\mathcal{B}$ -MATRIX OF A LINEAR TRANSFORMATION ON OTHER FUNCTIONS. Let  $\text{Fun}(\mathbb{R}, \mathbb{R})$  be the vector space of all real valued functions. Let  $S = \text{Span}\{\sin(x), \cos(x)\}$ .

- (1) Are  $\sin(x)$  and  $\cos(x)$  linearly independent?<sup>4</sup>
- (2) Find a basis  $\mathcal{B}$  for  $S$ . What is  $\dim(S)$ ?
- (3) Consider the linear transformation  $D : S \rightarrow S$  given by  $D(f(x)) = \frac{df}{dx}$ . Find the  $\mathcal{B}$ -matrix for  $D$ .
- (4) Find the  $\mathcal{B}$ -matrix for  $D^2$ .

F. THE  $\mathcal{B}$ -MATRIX OF A LINEAR TRANSFORMATION ON MATRICES. Consider the vector space  $M_{2 \times 2}$  of  $2 \times 2$  matrices. Take the basis  $\mathcal{B} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ . Let  $F : M_{2 \times 2} \rightarrow M_{2 \times 2}$  be

the function  $F(X) = \begin{bmatrix} 4 & -6 \\ -2 & 3 \end{bmatrix} X$ .

- (1) Show that the function  $F$  is a linear transformation.
- (2) Find the  $\mathcal{B}$ -matrix for  $F$ .
- (3) Find a basis for the null space of  $[F]_{\mathcal{B}}$ . Use this to find a basis for the kernel of  $F$ .
- (4) Find a basis for the column space of  $[F]_{\mathcal{B}}$ . Use this to find a basis for the range of  $F$ .
- (5) Let  $G : M_{2 \times 2} \rightarrow M_{2 \times 2}$  be the function  $G(X) = X + \begin{bmatrix} 4 & -6 \\ -2 & 3 \end{bmatrix}$ . Can you find the  $\mathcal{B}$ -matrix of  $G$ ?

Recall from last time that  $P_{\mathcal{C} \leftarrow \mathcal{B}}$  is the matrix such that  $P_{\mathcal{C} \leftarrow \mathcal{B}} \cdot [\mathbf{v}]_{\mathcal{B}} = [\mathbf{v}]_{\mathcal{C}}$  for all  $\mathbf{v} \in V$ . If  $\mathcal{B}$  and  $\mathcal{C}$  are two different bases for  $V$ , and  $T : V \rightarrow V$  is a linear transformation, then  $[T]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} \cdot [T]_{\mathcal{B}} \cdot P_{\mathcal{B} \leftarrow \mathcal{C}}^{-1}$ .

G. MATRICES FOR LINEAR TRANSFORMATIONS AND DIAGONALIZATION.

- (1) Explain why the formula  $[T]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} \cdot [T]_{\mathcal{B}} \cdot P_{\mathcal{B} \leftarrow \mathcal{C}}^{-1}$  is true.
- (2) If  $V = \mathbb{R}^n$  and  $\mathcal{C}$  is the standard basis  $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  explain how  $P_{\mathcal{C} \leftarrow \mathcal{B}}$  and  $P_{\mathcal{B} \leftarrow \mathcal{C}}^{-1}$  are related to  $P_{\mathcal{B}} = [\mathbf{b}_1 \ \cdots \ \mathbf{b}_n]$ .
- (3) If  $V = \mathbb{R}^n$  and  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  are all eigenvectors for  $T$  with eigenvalues  $\lambda_1, \dots, \lambda_n$  (respectively) use the definition of  $\mathcal{B}$ -matrix to compute  $[T]_{\mathcal{B}}$ .
- (4) In the setting of part (2) and (3), plug in all the pieces into the formula  $[T]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} \cdot [T]_{\mathcal{B}} \cdot P_{\mathcal{B} \leftarrow \mathcal{C}}^{-1}$ , and compare to the formula on the first page.
- (5) Explain the following: two matrices are similar if they correspond to the same linear transformation in different bases.
- (6) Explain the following: an  $n \times n$  matrix  $A$  is diagonalizable if and only if there is a basis  $\mathcal{B}$  of  $\mathbb{R}^n$  such that the  $\mathcal{B}$ -matrix of the transformation  $\mathbf{x} \mapsto A\mathbf{x}$  is a diagonal matrix.

<sup>4</sup>Hint: if  $a \sin(x) + b \cos(x) = 0$ , plug in  $x = 0$  and  $x = \pi/2$ .