

Learning Objectives

- Determine whether a specified vector is in the range of a matrix transformation
- Determine whether a transformation is linear

Introduction to Linear Transformations

It turns out that a matrix equation  $A\mathbf{x} = \mathbf{b}$  can arise in linear algebra (and in its applications) in a way that is not directly connected with linear combinations of vectors.

We can think of the matrix  $A$  as an object that “acts” on a vector  $\mathbf{x}$  by multiplication to produce a new vector called  $A\mathbf{x}$ .

**Example:** 
$$\begin{bmatrix} 2 & -4 \\ 3 & -6 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -8 \\ -12 \\ -4 \end{bmatrix} \qquad \begin{bmatrix} 2 & -4 \\ 3 & -6 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} \phantom{-8} \\ \phantom{-12} \\ \phantom{-4} \end{bmatrix}$$

If  $A$  is an  $m \times n$  matrix, then solving  $A\mathbf{x} = \mathbf{b}$  amounts to finding all \_\_\_\_\_ in  $\mathbb{R}^n$  which are transformed into the vector  $\mathbf{b}$  in \_\_\_\_\_ under the “action” of multiplication by  $A$ .

**Definition:** A \_\_\_\_\_ (or **function** or **mapping**)  $T$  from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  is a rule that assigns to each vector  $\mathbf{x}$  in  $\mathbb{R}^n$  a vector  $T(\mathbf{x})$  in  $\mathbb{R}^m$ .

The set  $\mathbb{R}^n$  is called the \_\_\_\_\_ of  $T$  and  $\mathbb{R}^m$  is called the \_\_\_\_\_ of  $T$ .

For  $\mathbf{x}$  in  $\mathbb{R}^n$ , the vector  $T(\mathbf{x})$  in  $\mathbb{R}^m$  is called the \_\_\_\_\_ of  $\mathbf{x}$ .

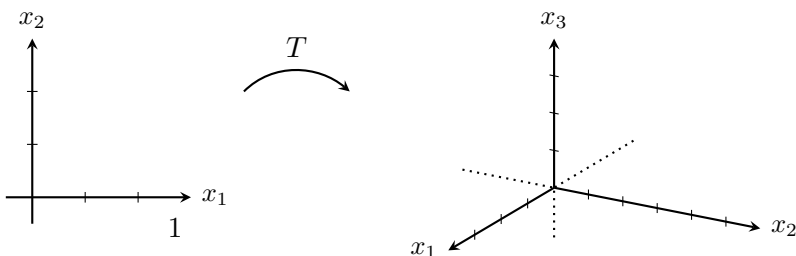
The set of all images  $T(\mathbf{x})$  is called the \_\_\_\_\_ of  $T$ .

Matrix Transformations

**Example:** Let  $A = \begin{bmatrix} 1 & 0 \\ 2 & 1 \\ 0 & 1 \end{bmatrix}$ . Define a transformation  $T : \text{---} \rightarrow \text{---}$  by  $T(\mathbf{x}) = A\mathbf{x}$ .

Describe the image of  $\mathbf{u} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$  under the transformation  $T$ .

$$T(\mathbf{u}) = A\mathbf{u} =$$



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**Example:** Let  $A = \begin{bmatrix} 1 & -2 & 3 \\ -5 & 10 & -15 \end{bmatrix}$ ,  $\mathbf{b} = \begin{bmatrix} 2 \\ -10 \end{bmatrix}$ , and  $\mathbf{c} = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$ .

Define a transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ .

a. Find an  $\mathbf{x}$  in  $\mathbb{R}^3$  whose image under  $T$  is  $\mathbf{b}$ .

b. Is there more than one  $\mathbf{x}$  whose image under  $T$  is  $\mathbf{b}$ ? (*uniqueness problem*)

c. Determine if  $\mathbf{c}$  is in the range of the transformation  $T$ . (*existence problem*)

Linear Transformations

**Definition:** A transformation  $T$  is \_\_\_\_\_ if

(i)  $T(\mathbf{u} + \mathbf{v}) = \underline{\hspace{2cm}}$  for all  $\mathbf{u}, \mathbf{v}$  in the domain of  $T$ ;

(ii)  $T(c\mathbf{u}) = \underline{\hspace{2cm}}$  for all scalars  $c$  and all  $\mathbf{u}$  in the domain of  $T$ .

Recall Theorem 1.5 says that if  $A$  is an  $m \times n$  matrix, then the transformation  $T(\mathbf{x}) = A\mathbf{x}$  has the properties

$$A(\mathbf{u} + \mathbf{v}) = \underline{\hspace{2cm}} \quad \text{and} \quad A(c\mathbf{u}) = \underline{\hspace{2cm}}$$

for all vectors  $\mathbf{u}$  and  $\mathbf{v}$  in  $\mathbb{R}^n$  and all scalars  $c$ .

Thus, we have the following important fact:

Every \_\_\_\_\_ transformation is a \_\_\_\_\_ transformation.

The definition of a linear transformation implies the following properties:

If  $T$  is a linear transformation, then

$$T(\mathbf{0}) = \underline{\hspace{2cm}}$$

and

$$T(c\mathbf{u} + d\mathbf{v}) = \underline{\hspace{2cm}} + \underline{\hspace{2cm}}$$

for all vectors  $\mathbf{u}, \mathbf{v}$  in the domain of  $T$  and all scalars  $c, d$ .

Note that if a transformation satisfies the second property above, then it must be linear.

Repeated application of this property gives us a useful generalization, referred to as the **superposition principle**:

$$T(c_1\mathbf{v}_1 + \cdots + c_p\mathbf{v}_p) = \underline{\hspace{2cm}}$$

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**Example:** Define a transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  by  $T(\mathbf{x}) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ 0 \end{bmatrix}$ .

Show that  $T$  is a linear transformation.

**Example:** Define  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  such that  $T(\mathbf{x}) = \begin{bmatrix} |x_1 + x_3| \\ 2 + 5x_2 \end{bmatrix}$ .

Show that  $T$  is **not** a linear transformation.